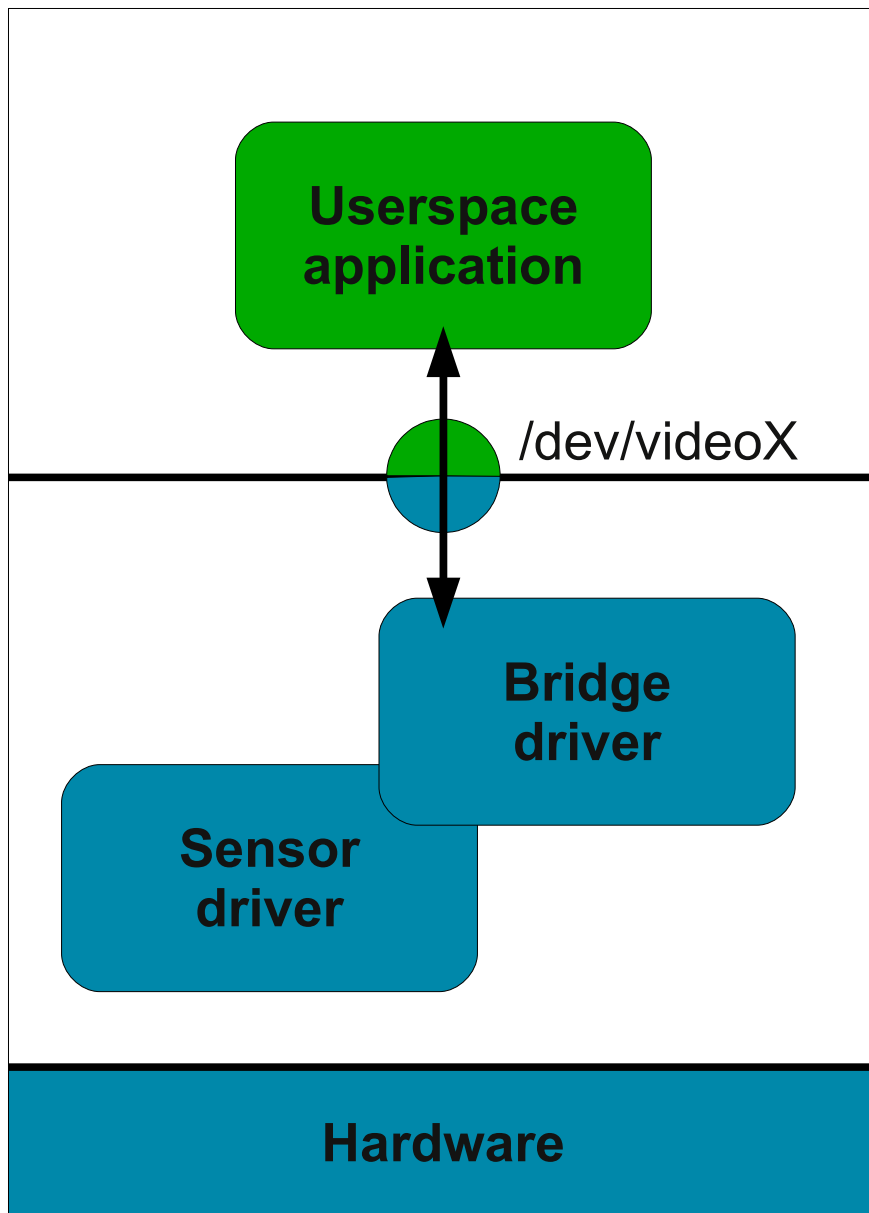


# Media controller

## Goals, architecture and roadmap

V4L2 Helsinki Summit 2010-06-14

Laurent Pinchart  
laurent.pinchart@ideasonboard.com



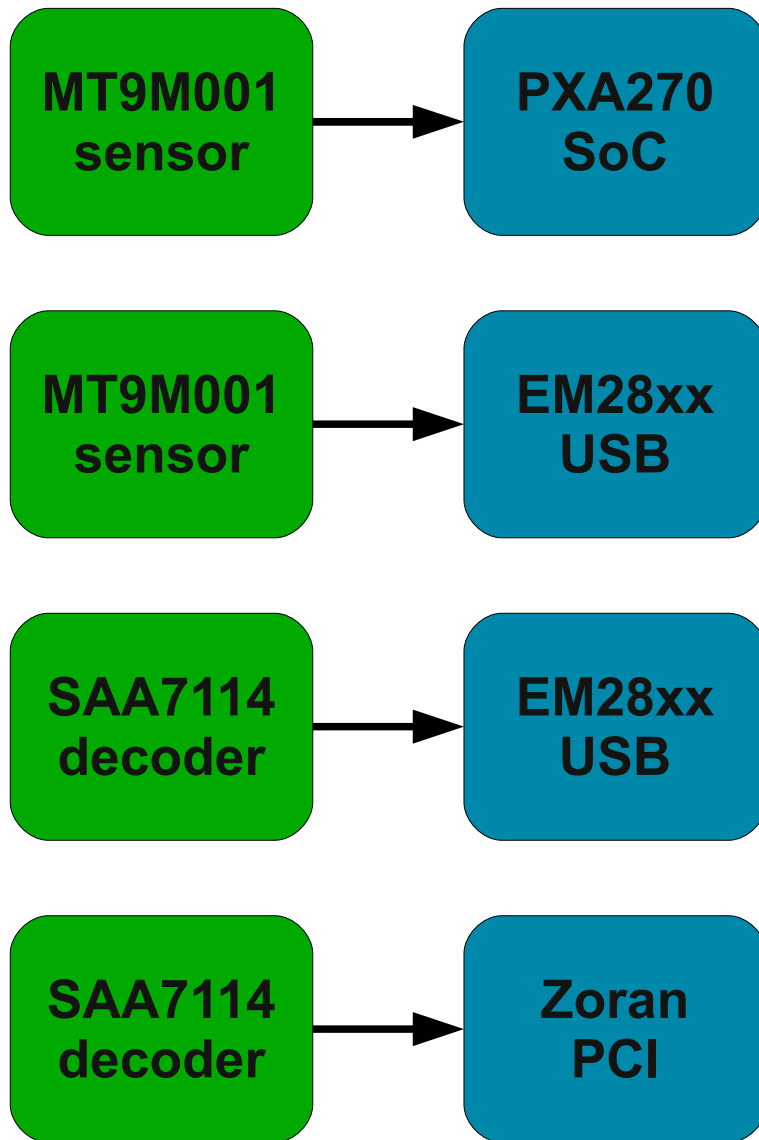
## Embedded SoC camera

- `soc_camera`
- `v4l2_device`
- `v4l2_subdev`

## Userspace library

- Format conversion
- Post-processing

# Embedded camera



- In-kernel functional abstraction layer developed by Hans Verkuil
- Designed for on-board external devices (sensors, tuners, audio codecs, ...)
- Reusability, Reusability, Reusability

## V4L2 subdevice

```
struct v4l2_subdev_ops {
    const struct v4l2_subdev_core_ops    *core;
    const struct v4l2_subdev_tuner_ops   *tuner;
    const struct v4l2_subdev_audio_ops   *audio;
    const struct v4l2_subdev_video_ops   *video;
    const struct v4l2_subdev_ir_ops      *ir;
    const struct v4l2_subdev_sensor_ops  *sensor;
};
```

- Hardware independent
- Bus type independent



# V4L2 subdevice operations

# V4L2 device

# V4L2 subdevice

device\_driver::probe called

Register hardware device

i2c\_new\_device

Retrieve subdevice pointer

i2c\_get\_client\_data

Register subdevice

v4l2\_device\_register\_subdev

v4l2\_subdev\_call(core::s\_config)

device\_driver::probe called

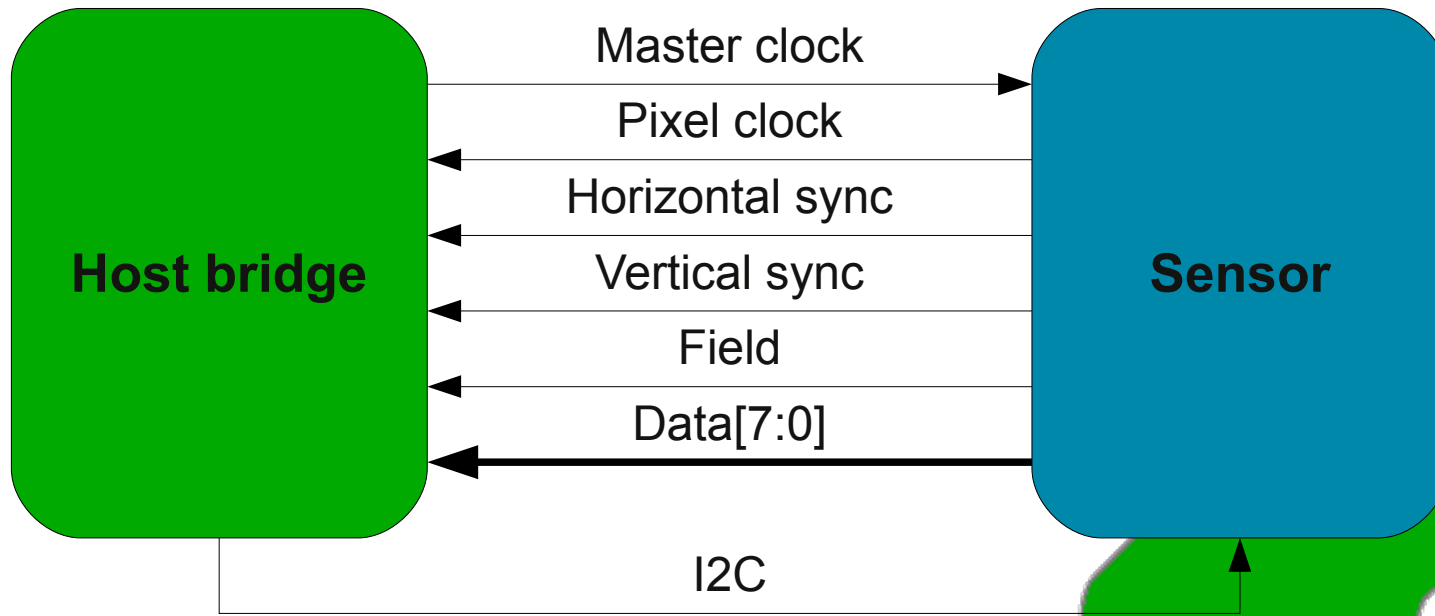
Subdevice initialization

Subdevice setup

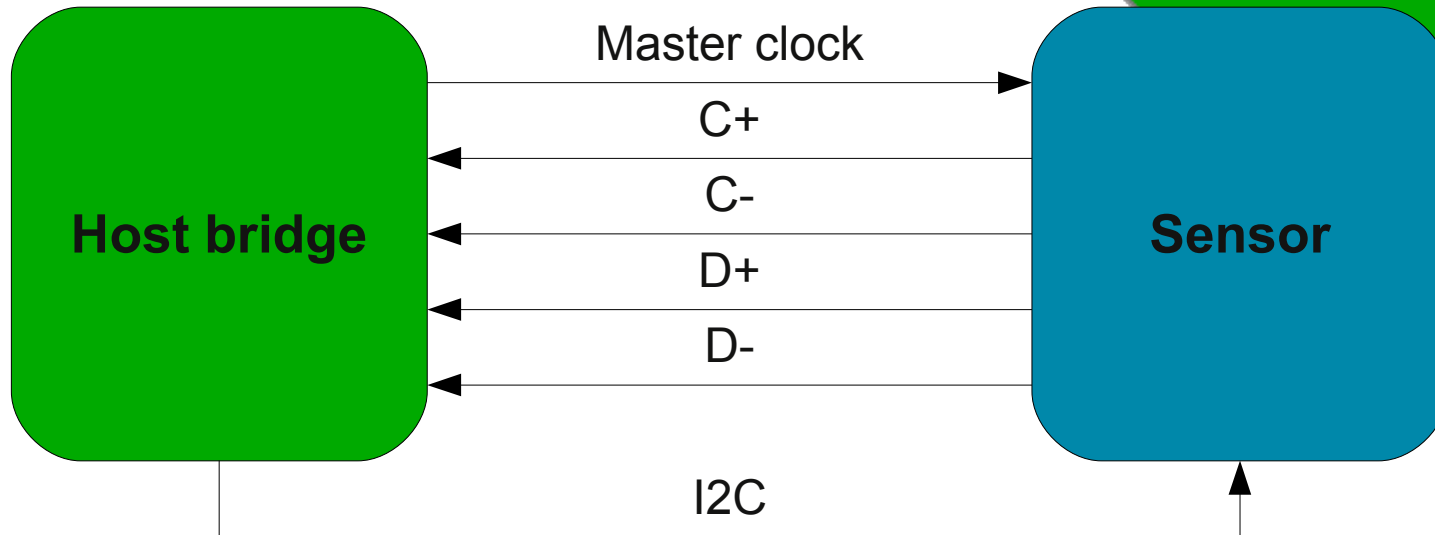
v4l2\_i2c\_new\_subdev\_board

# V4L2 subdevice registration

## Parallel interface



## Serial interface (CSI)



# SoC Camera

## V4L2 device

## V4L2 subdevice

V4L2 call (VIDIOC\_S\_FMT)

v4l2\_subdev\_call(video::s\_fmt)

Configure the sensor scaler

Success ?

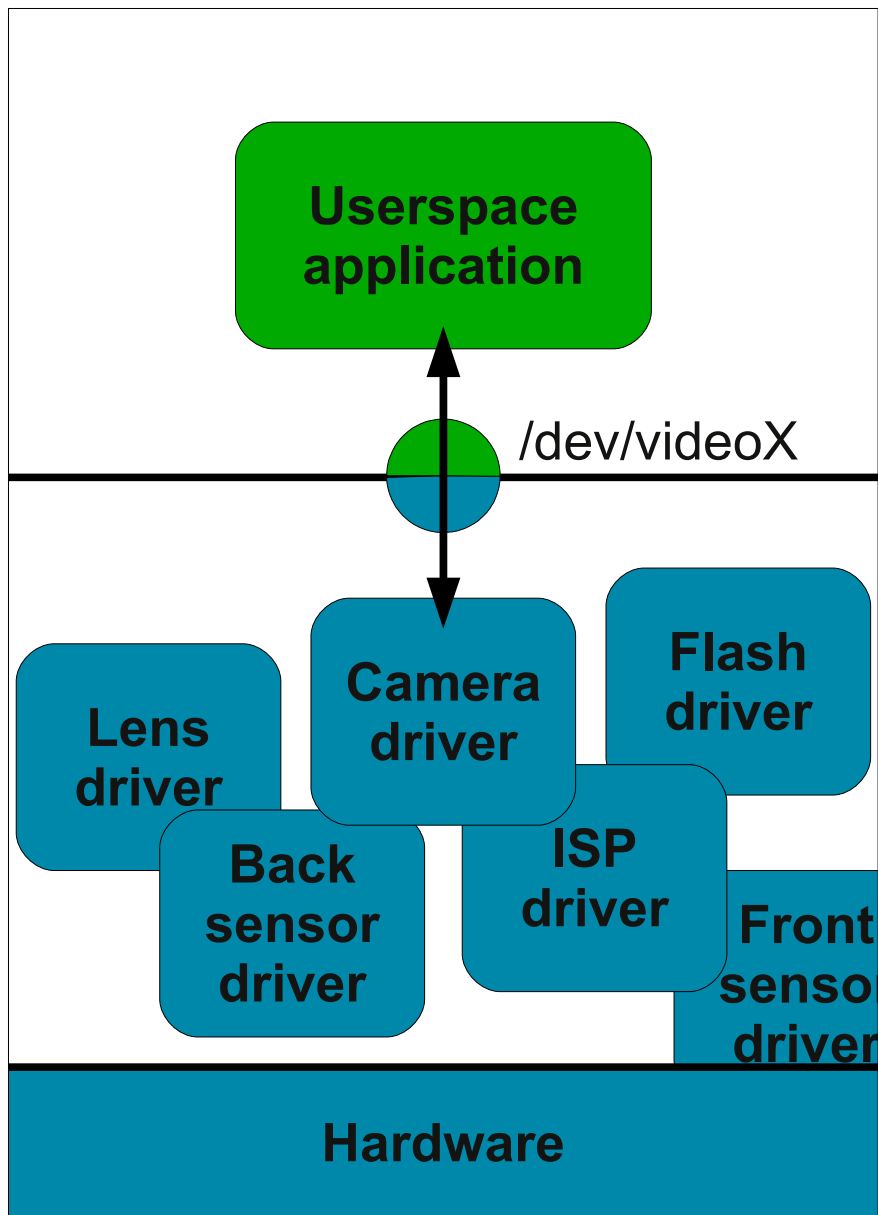
return

Failure ?

Configure the  
bridge scaler

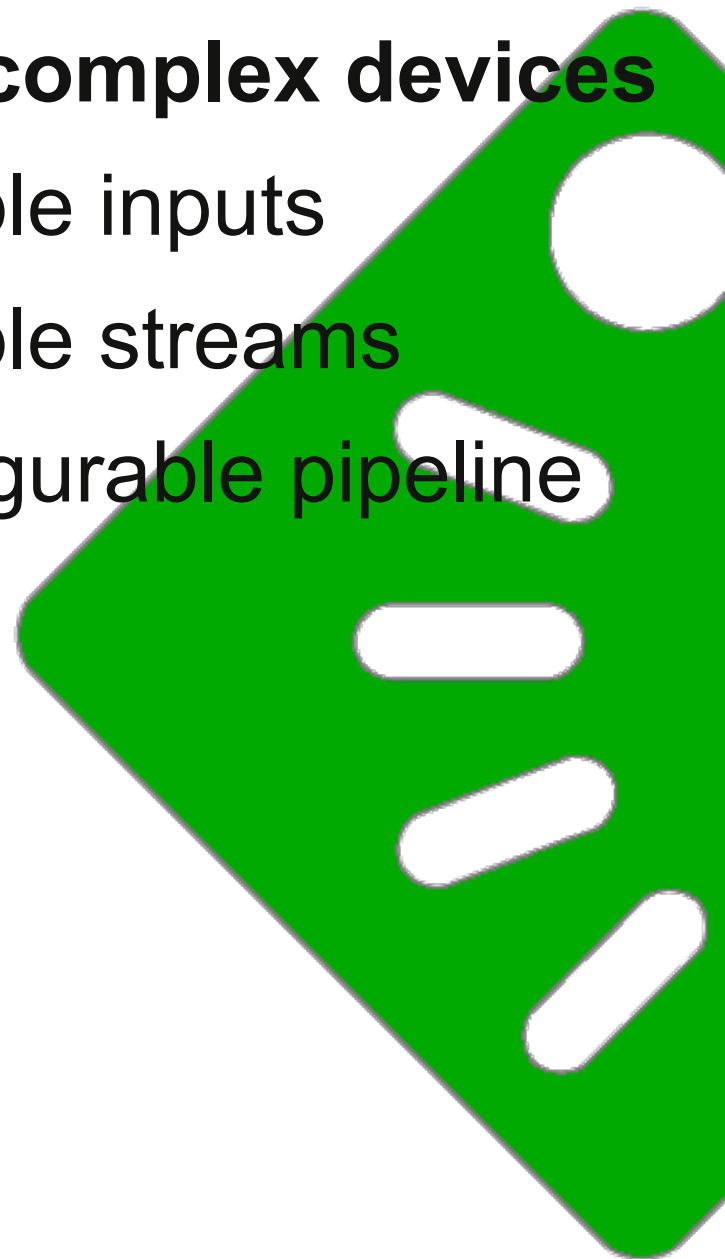
- **How do we decide where to perform scaling ?**
  - On the sensor side for higher frame rates ?
  - On the host side for better quality ?

# V4L2 subdevice usage



## Highly complex devices

- Multiple inputs
- Multiple streams
- Configurable pipeline



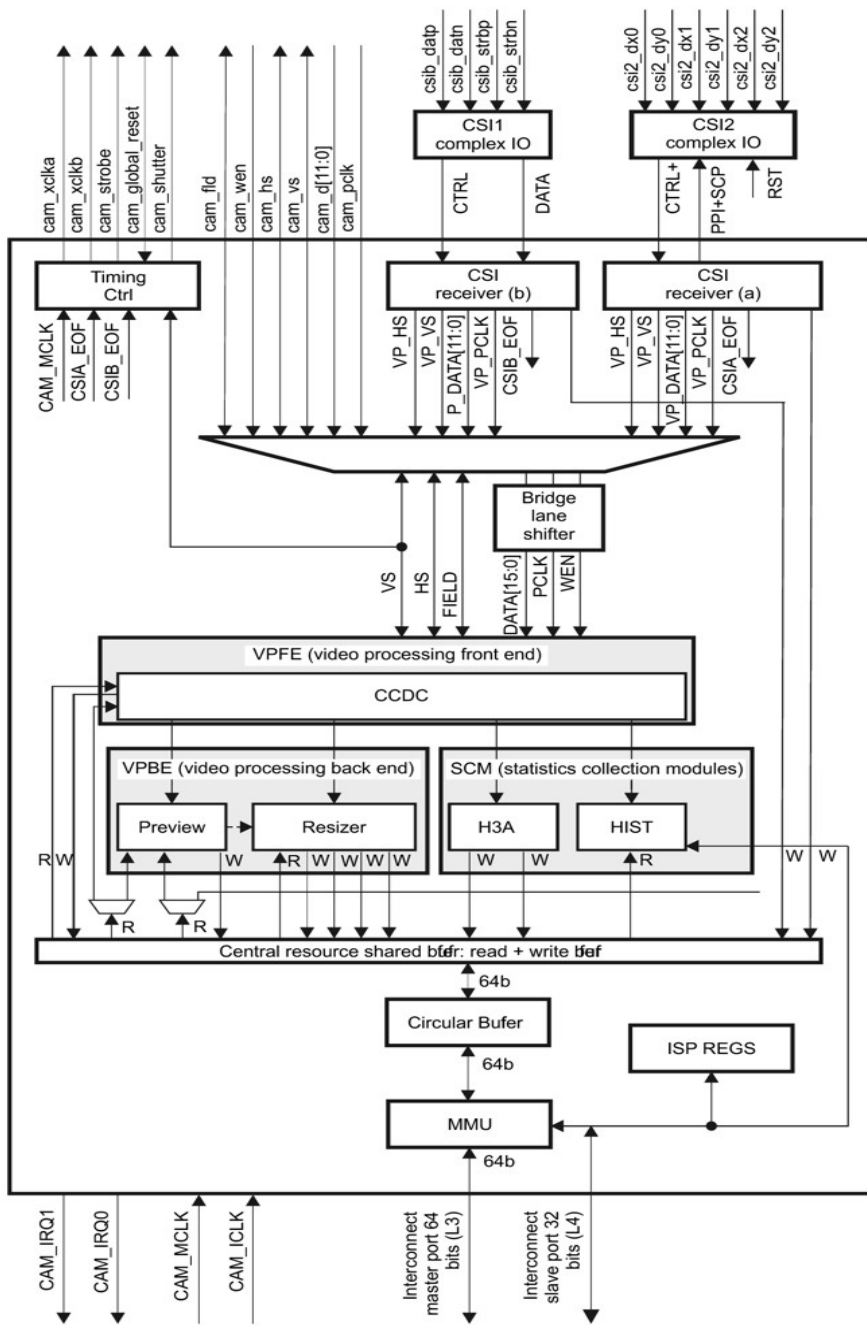
# Embedded mess



# OMAP3430 ISP

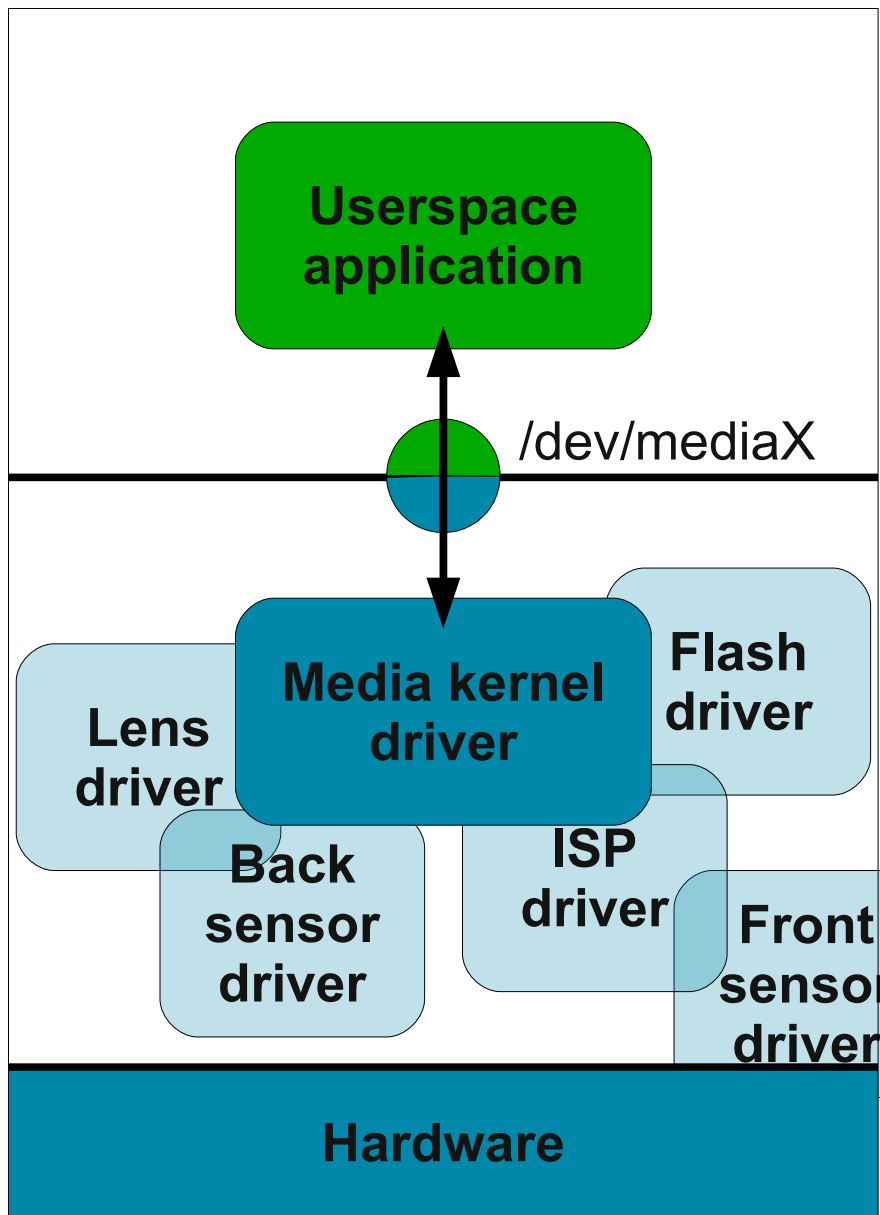
- Reconfigurable pipeline
- Parallel processing
- Memory-to-memory paths
- Fine-grain parameters

How do we handle the zillion configuration options through a single video device ?



Drawing is © Texas Instrument

# OMAP3430 ISP



## What ?

- Just a device. Similar to v4l2\_device, but more abstract.

## Why ?

- To let userspace applications have fine grain control over all the media device parameters.

# Media controller – What and why

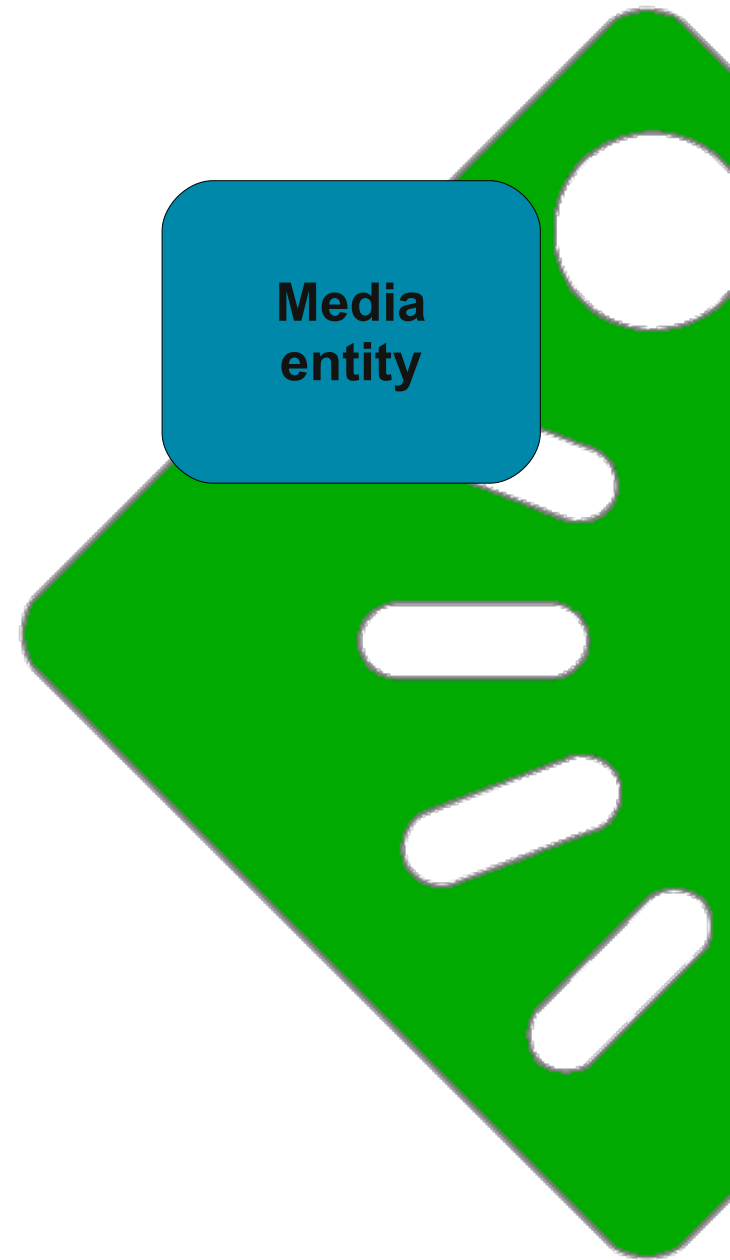
# How ?

- Expose the media device topology to userspace as a graph of building blocks called **entities** connected through **pads**.
- Activate/deactivate **links** from userspace.
- Give access to entities **internal parameters** through read/write/ioctl calls.
- Configure image **streaming parameters** at each pad.

## Media controller - How

```
struct media_entity
{
    u32 id;
    const char *name;
    u32 type;
    u32 subtype;
    ...
};
```

- media\_entity::type
  - MEDIA\_ENTITY\_TYPE\_NODE
  - MEDIA\_ENTITY\_TYPE\_SUBDEV



# Media entity

```

struct media_entity
{
    ...
    u8 num_pads;
    struct media_entity_pad *pads;
    ...
};

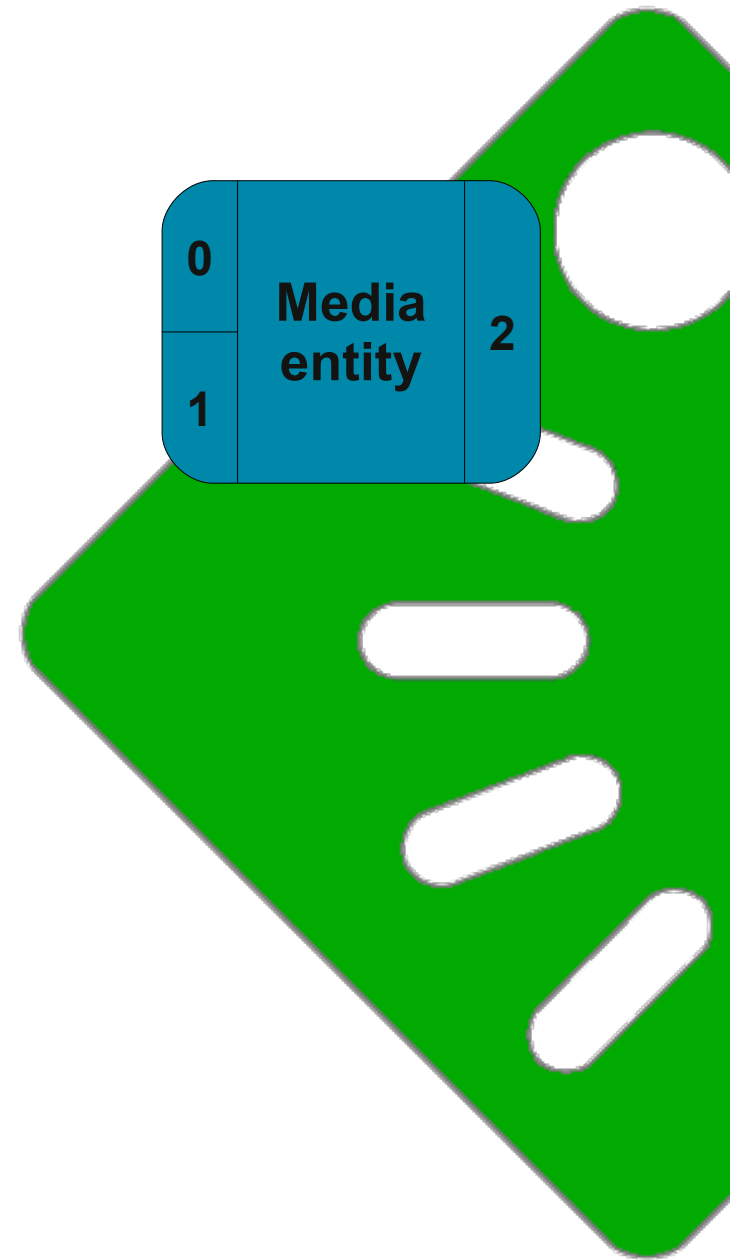
```

```

struct media_entity_pad
{
    u32 type;
    u32 index;
};

```

- `media_entity_pad::type`
  - `MEDIA_PAD_TYPE_INPUT`
  - `MEDIA_PAD_TYPE_OUTPUT`



# Media entity - Pads

```

struct media_entity
{
    ...
    u32 num_links;
    struct media_entity_link *links;
    ...
};

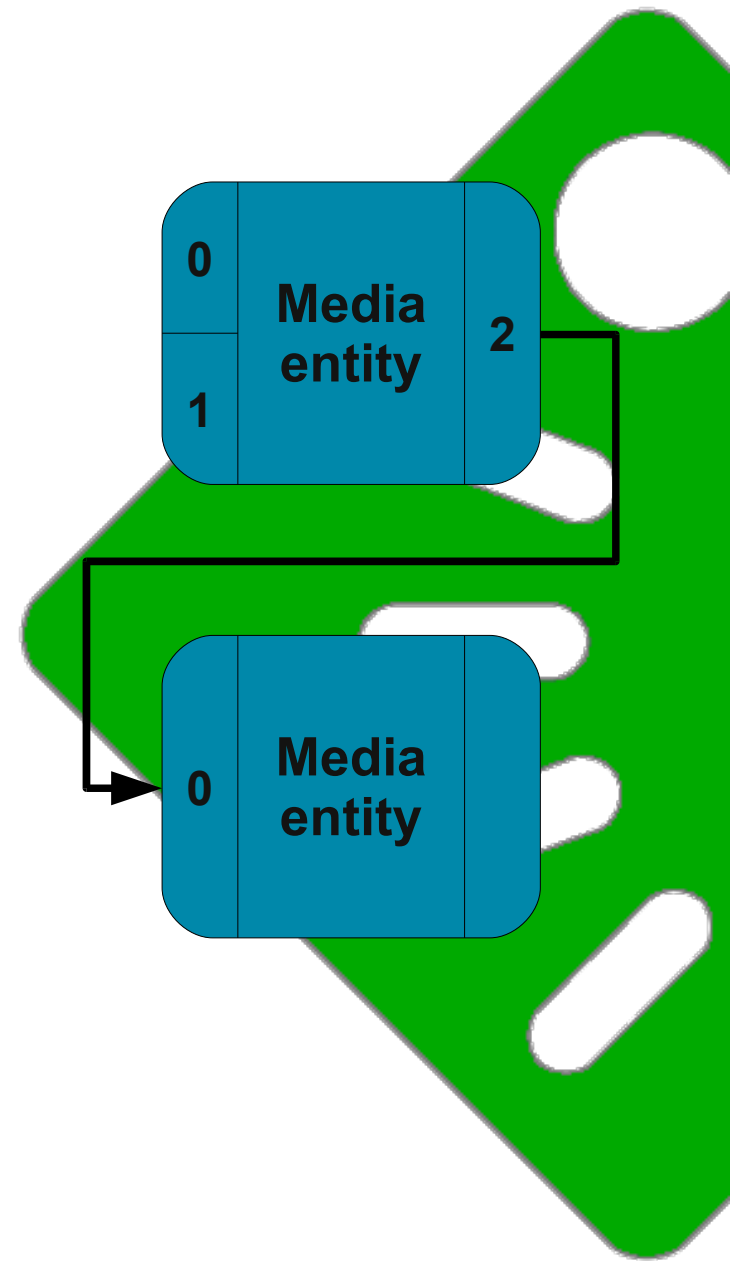
```

```

struct media_entity_link
{
    struct media_entity_pad *source;
    struct media_entity_pad *sink;
    u32 flags;
};

```

- media\_entity\_link::flags
  - MEDIA\_LINK\_FLAG\_ACTIVE
  - MEDIA\_LINK\_FLAG\_IMMUTABLE



# Media entity - Links

# Media entity

## Initialize entity

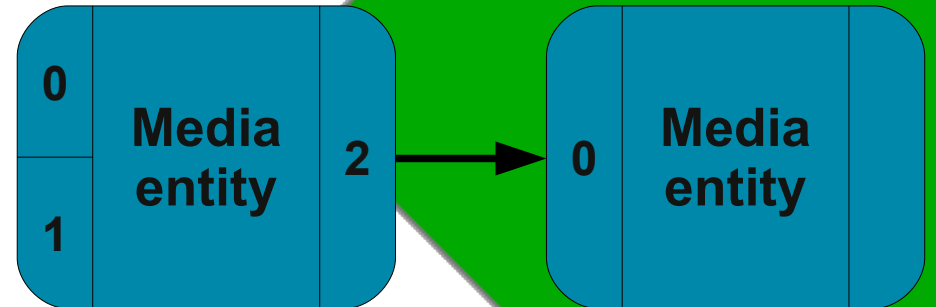
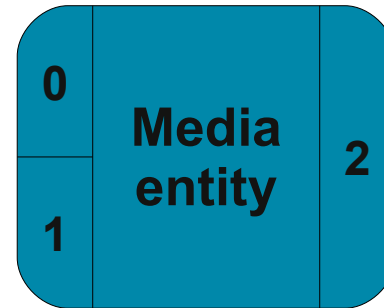
`media_entity_init`

## Create links

`media_entity_create_link`

## Register entity

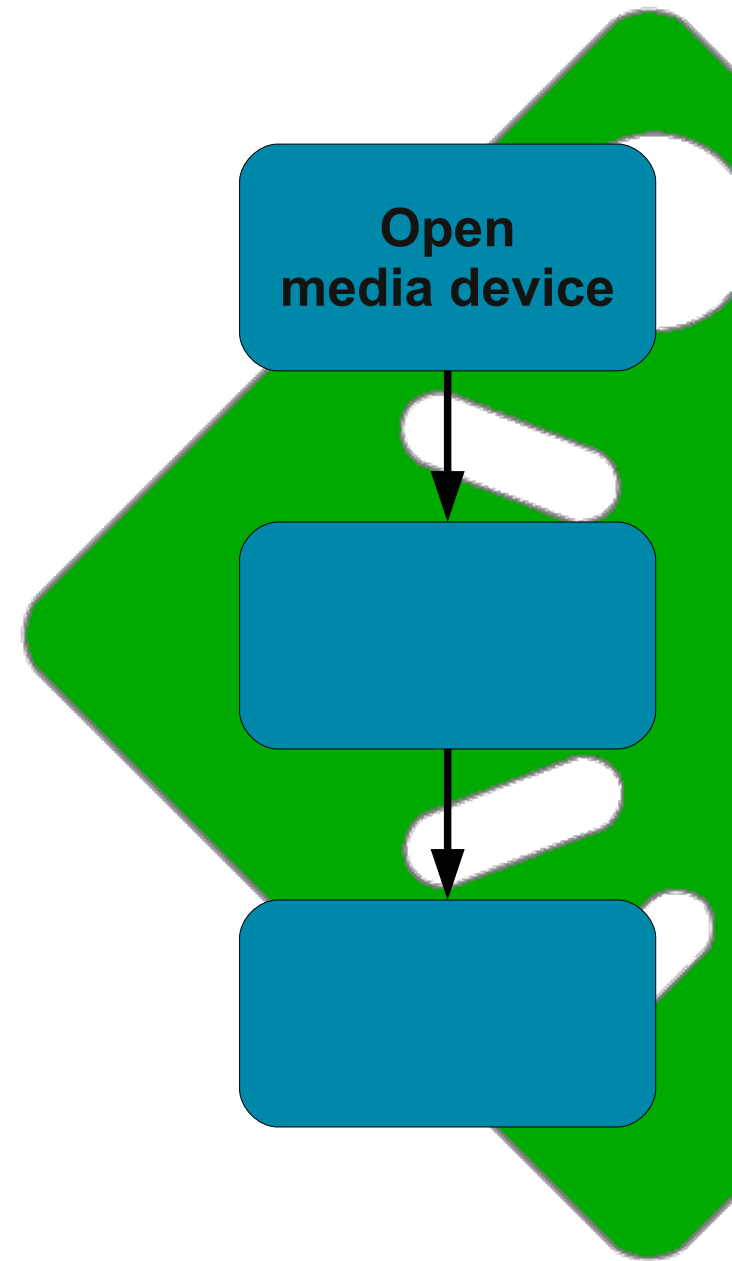
`media_device_register_entity`



# Media entity registration

```
int fd;
```

```
fd = open("/dev/media0", O_RDWR);
```



# Media controller – Userspace API



```
int fd;

fd = open("/dev/media0", O_RDWR);

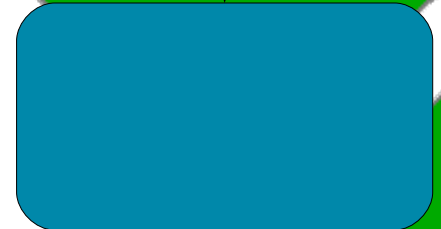
while (1) {
    struct media_user_entity entity;
    struct media_user_links links;

    ret = ioctl(fd, MEDIA_IOC_ENUM_ENTITIES, &entity);
    if (ret < 0)
        break;

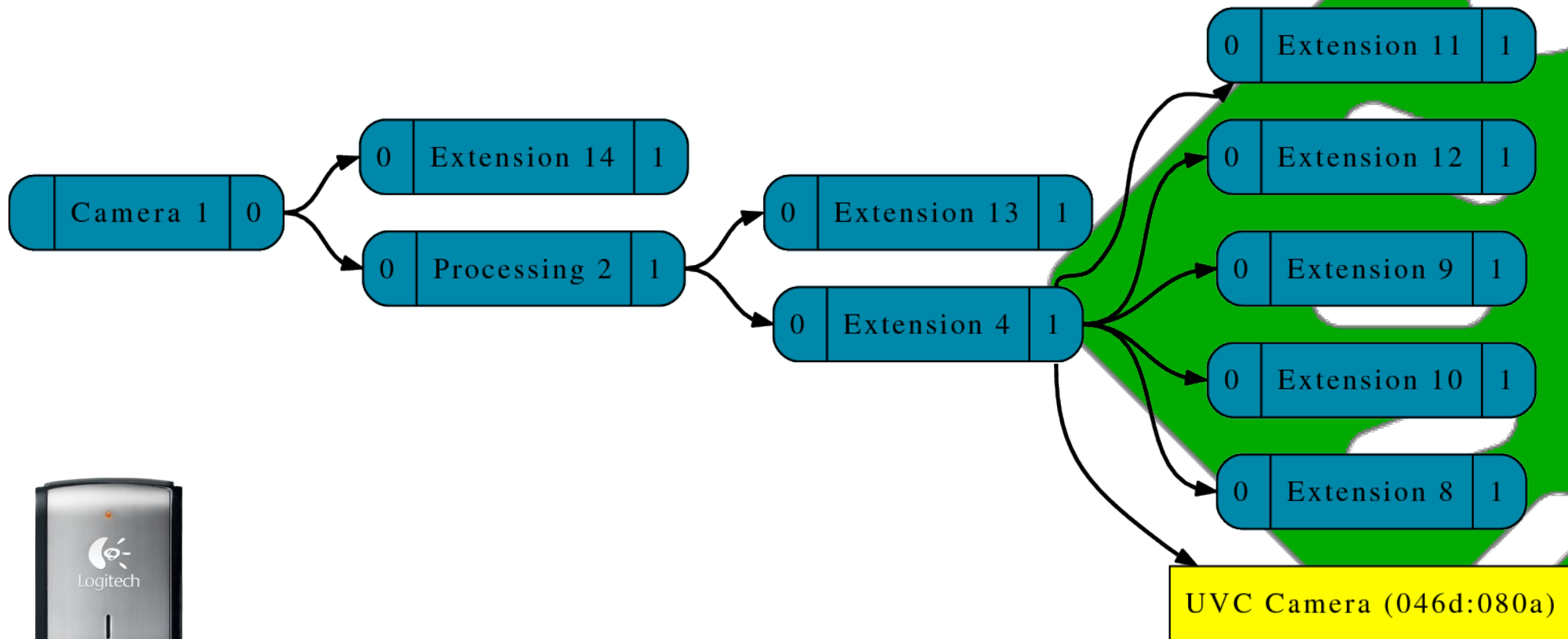
    while (1) {
        ret = ioctl(fd, MEDIA_IOC_ENUM_LINKS, &links);
        if (ret < 0)
            break;
    }
}
```

**Open  
media device**

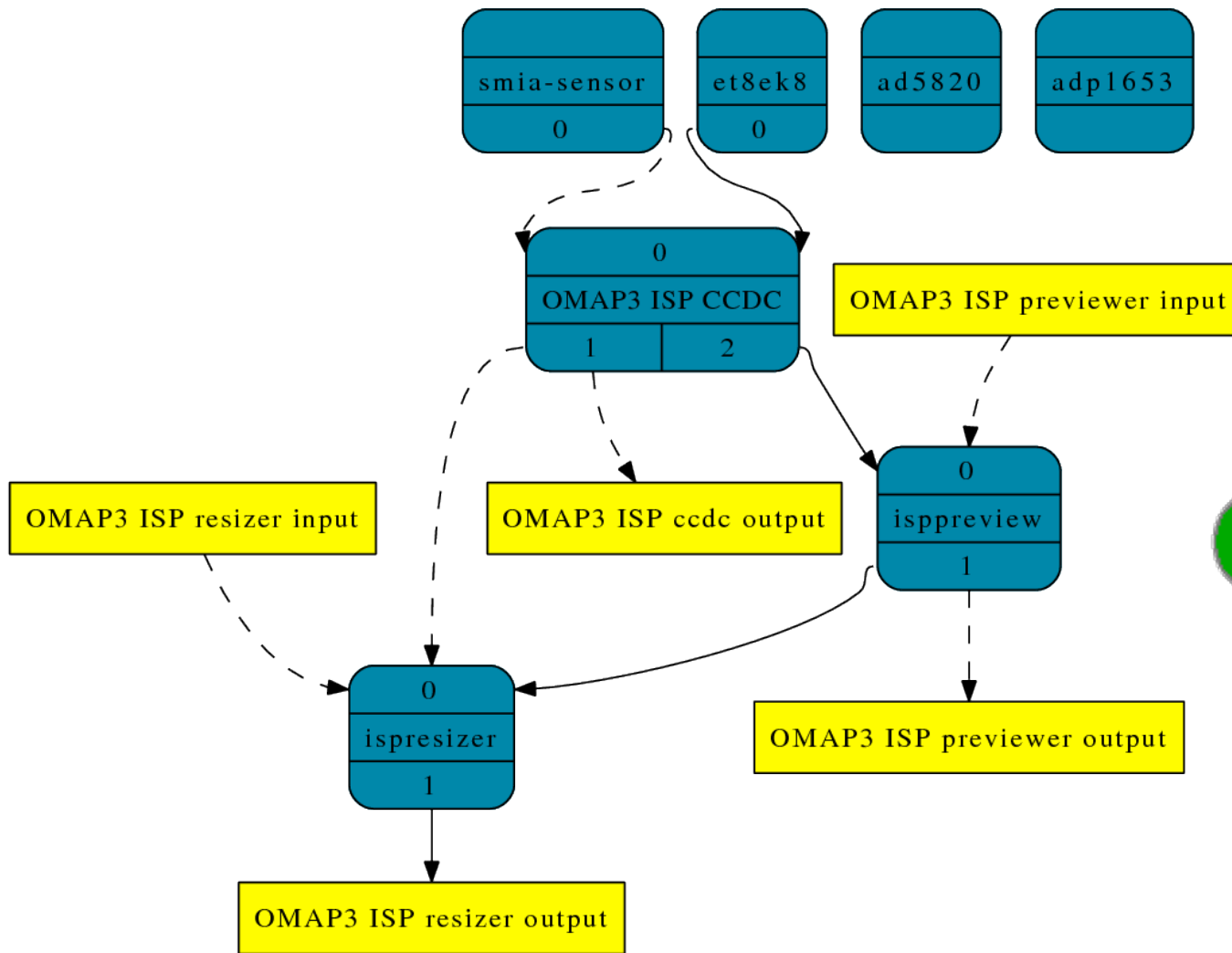
**Enumerate  
entities, pads  
and links**



# Media controller – Userspace API



# Logitech Portable Webcam C905



# Nokia N900

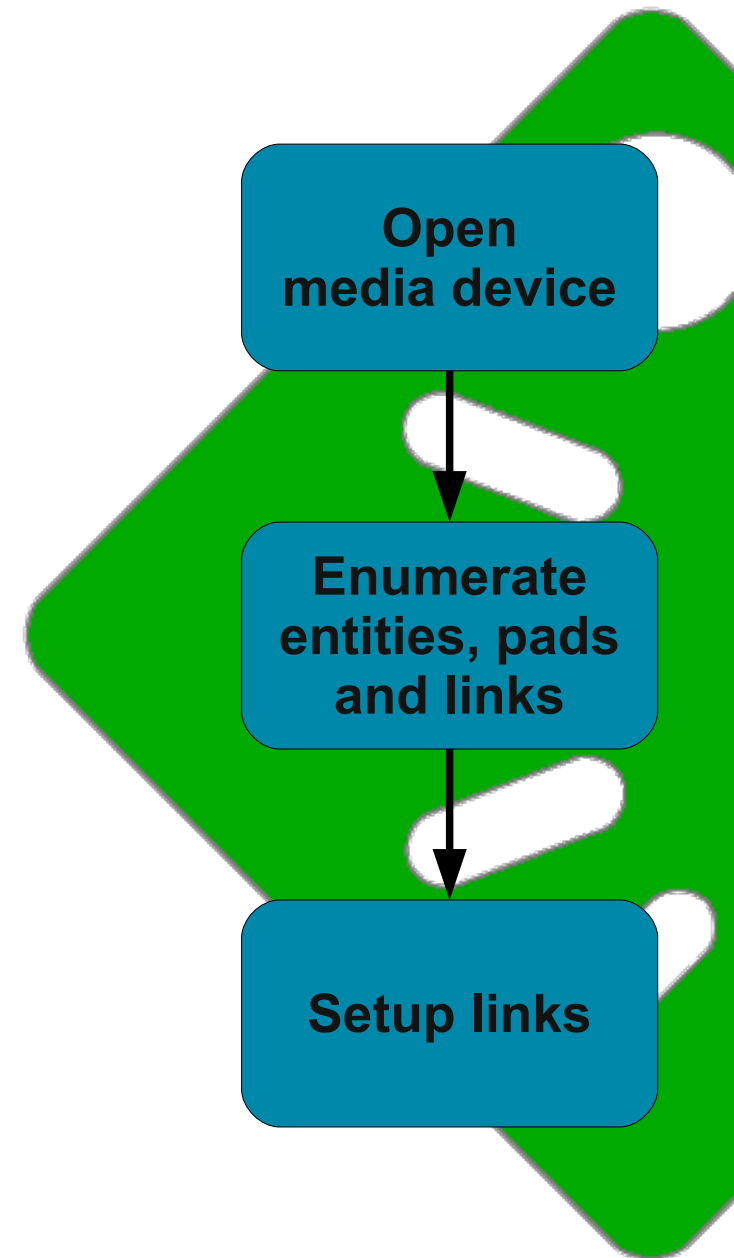
```
struct media_user_link link;

link.source.entity = OMAP3_ISP_ENTITY_CCDC;
link.source.index = 2;
link.sink.entity = OMAP3_ISP_ENTITY_PREVIEW;
link.sink.index = 0;
link.flags = 0;

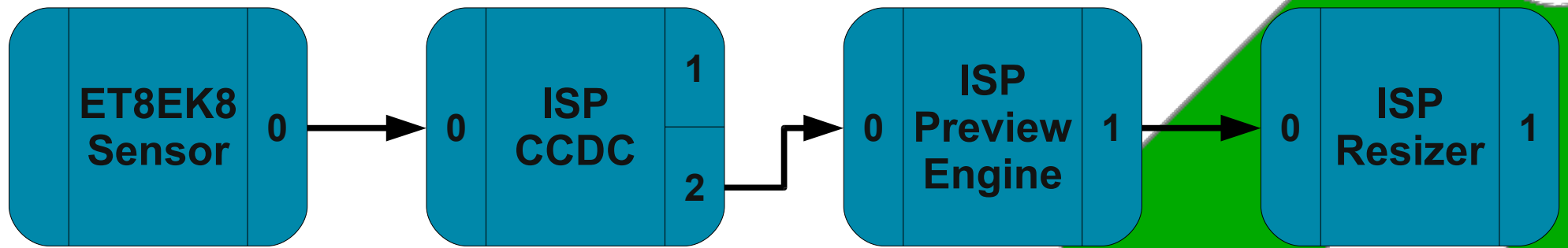
ioctl(fd, MEDIA_IOC_SETUP_LINK, &link);

link.source.entity = OMAP3_ISP_ENTITY_CCDC;
link.source.index = 1;
link.sink.entity = OMAP3_ISP_ENTITY_CCDC_OUT;
link.sink.index = 0;
link.flags = MEDIA_LINK_FLAG_ACTIVE;

ioctl(fd, MEDIA_IOC_SETUP_LINK, &link);
```



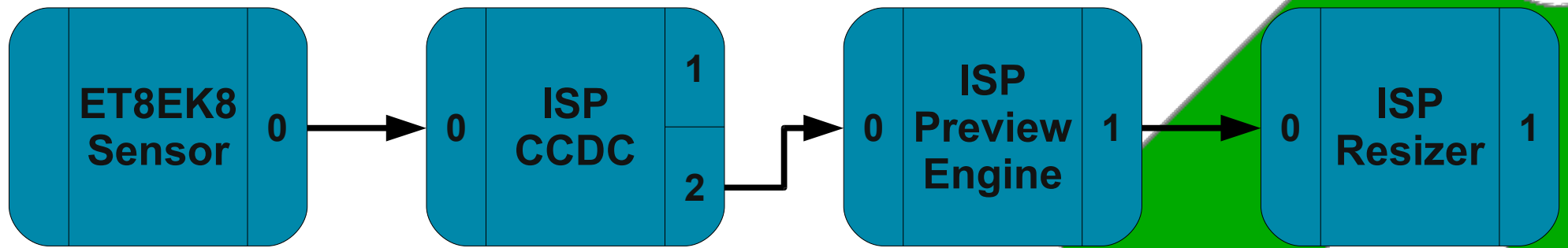
# Media controller – Userspace API



- White balance
- Faulty pixels correction
- White balance
- Faulty pixels correction

**The S\_CTRL API is not up to the job.**

# OMAP3430 ISP - Controls

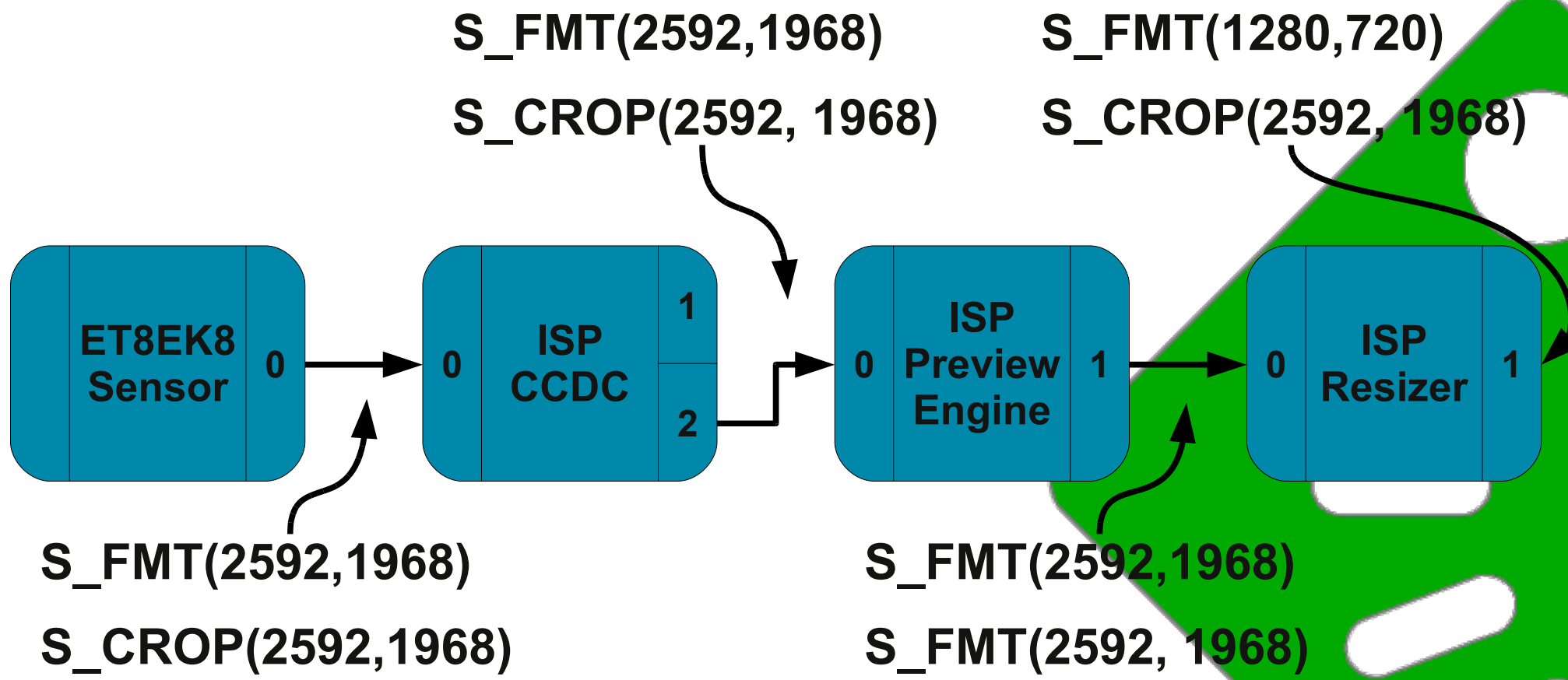


- Binning

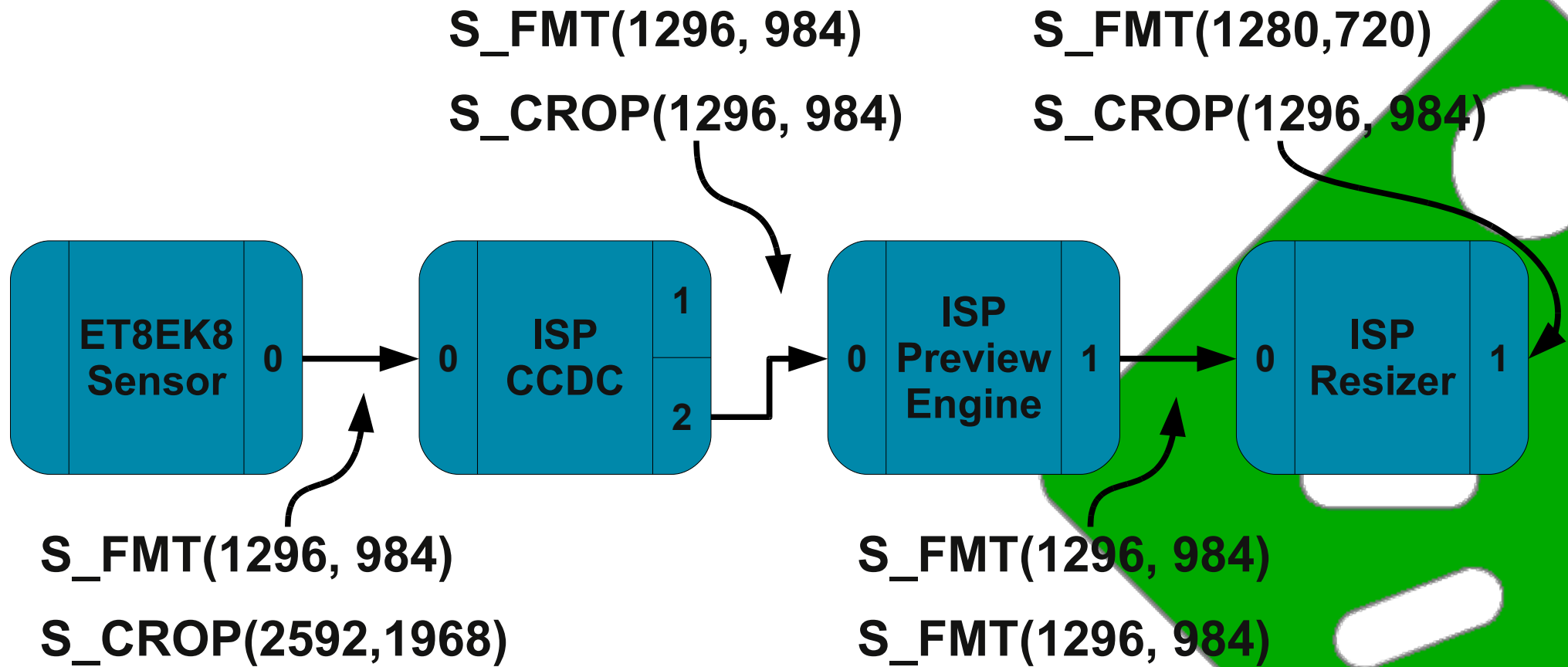
- Horizontal averaging

- Polyphase filter

# OMAP3430 ISP - Resizing



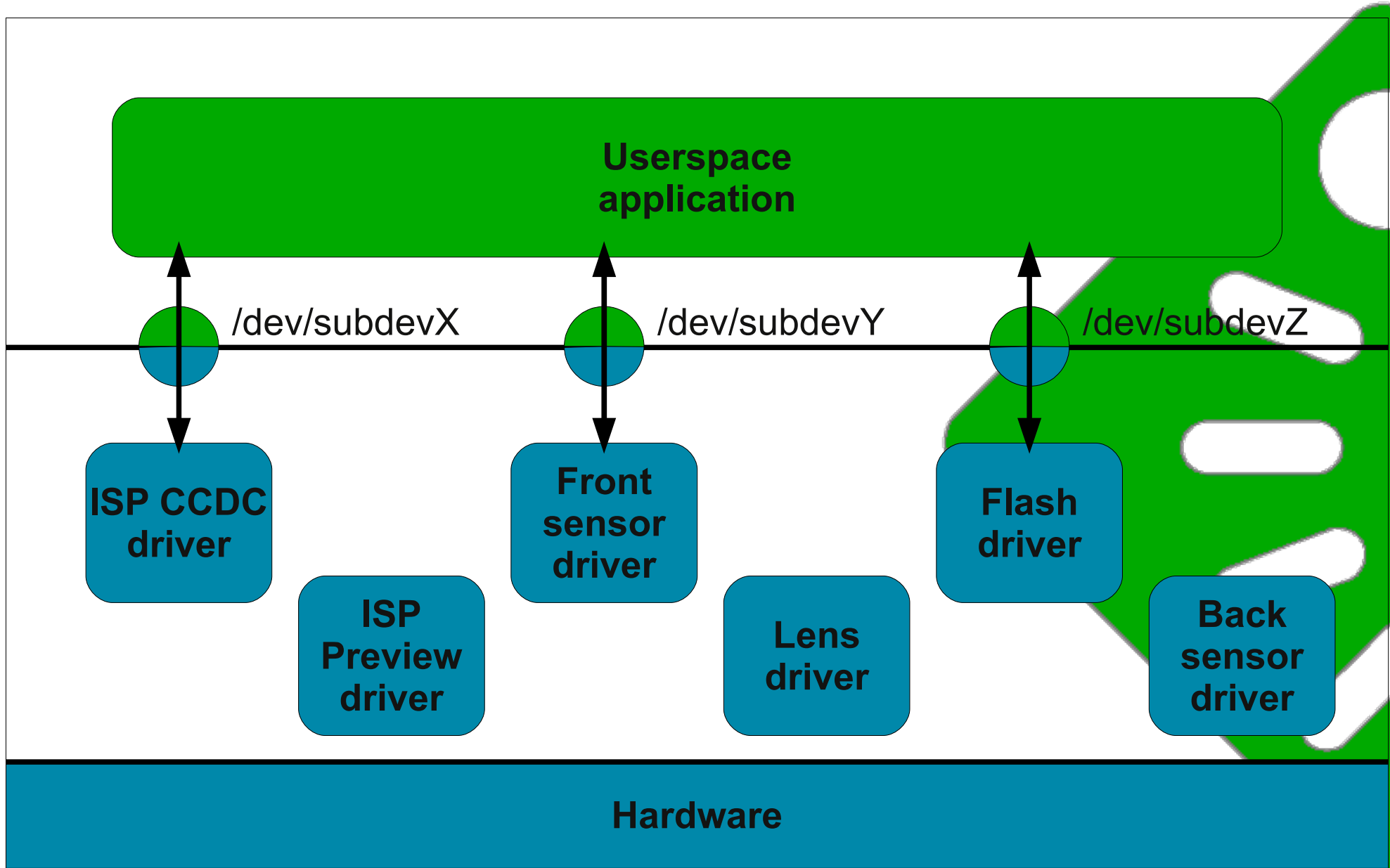
# OMAP3430 ISP – High quality



The S\_FMT/S\_CROP API is not up to the job.

# OMAP3430 ISP – High speed

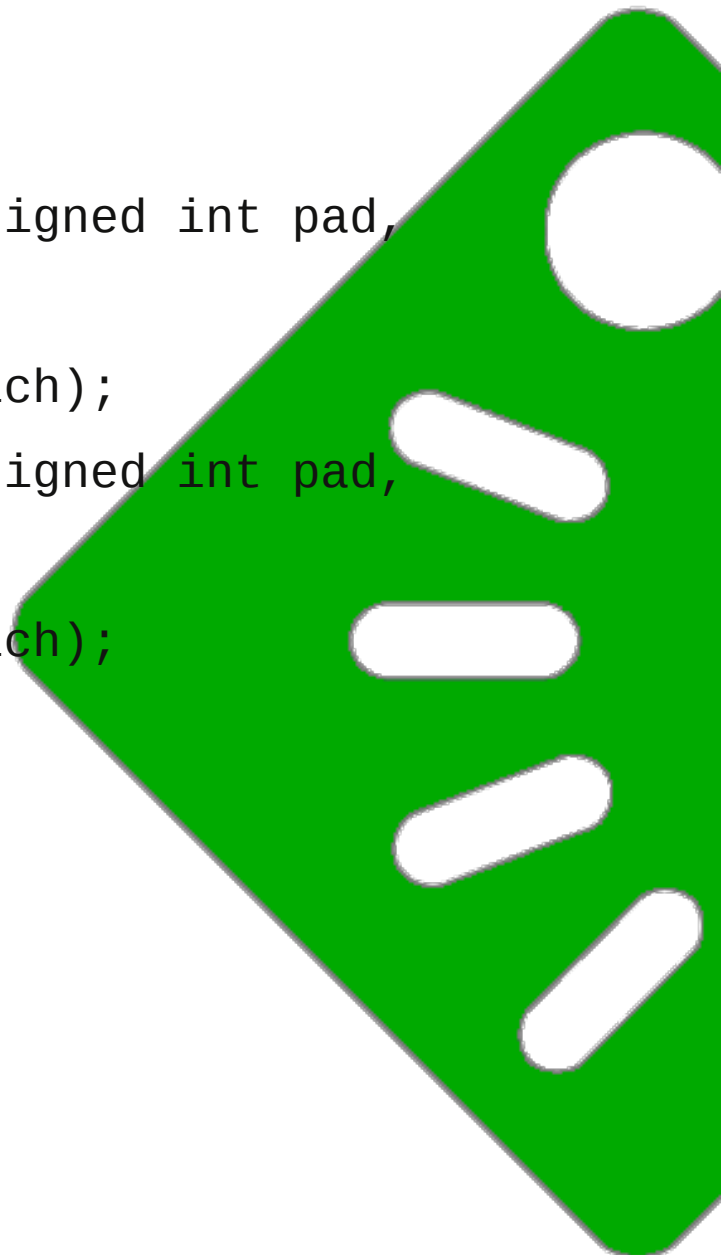




# V4L2 subdev userspace API

```
struct v4l2_subdev_pad_ops {
    ...
    int (*get_fmt)(struct v4l2_subdev *sd, unsigned int pad,
                  struct v4l2_format *fmt,
                  enum v4l2_subdev_format which);
    int (*set_fmt)(struct v4l2_subdev *sd, unsigned int pad,
                  struct v4l2_format *fmt,
                  enum v4l2_subdev_format which);
    ....
};

struct v4l2_subdev_ops {
    ...
    const struct v4l2_subdev_pad_ops *pad;
};
```



# V4L2 subdevice pad operations

## Is this V4L3 ?

- No, V4L2 is still alive and well
- Best effort to provide V4L2-only compatibility for existing applications (API and ABI)
- Advanced features will require Media Controller

## OMAP3430 ISP

- Default pipeline through /dev/video0 ?
- Limited set of resolutions, limited set of controls

# V4L2 plain API

## Retrieve statistics

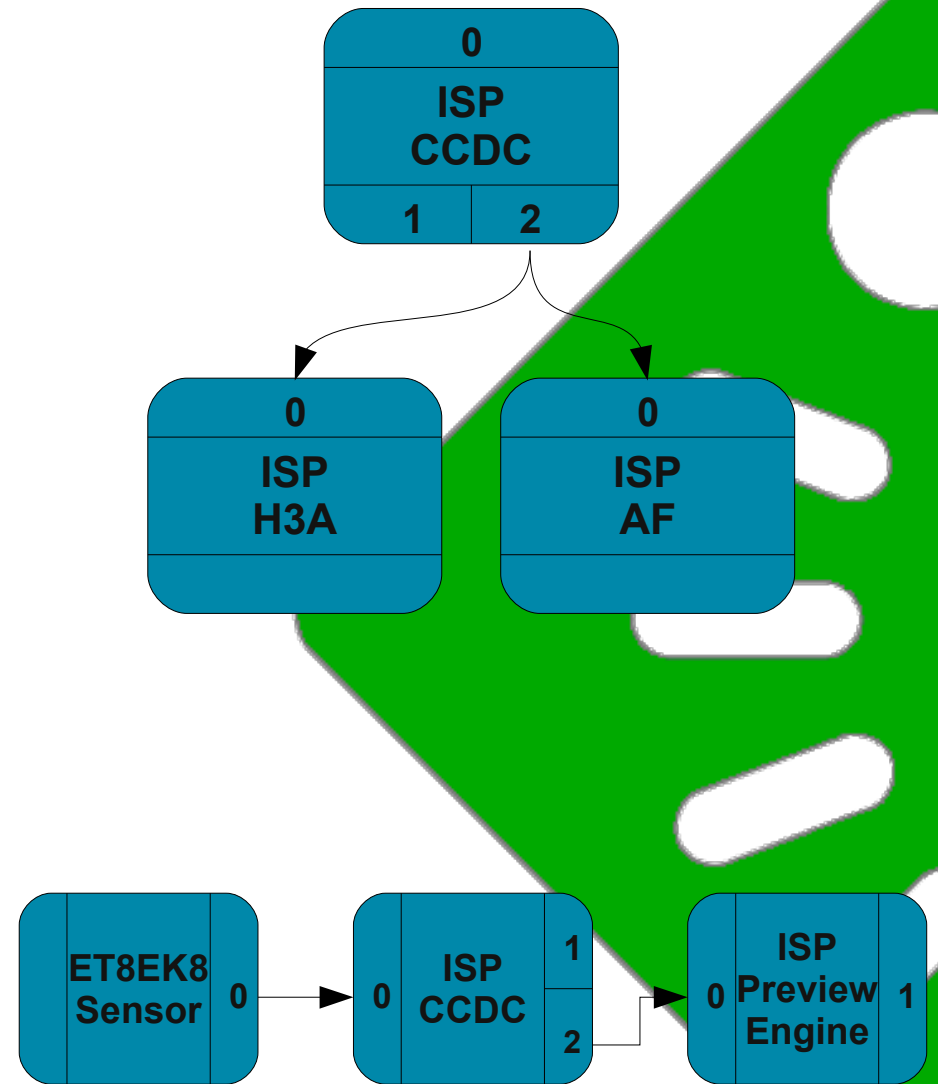
V4L2 events API

## Compute parameters

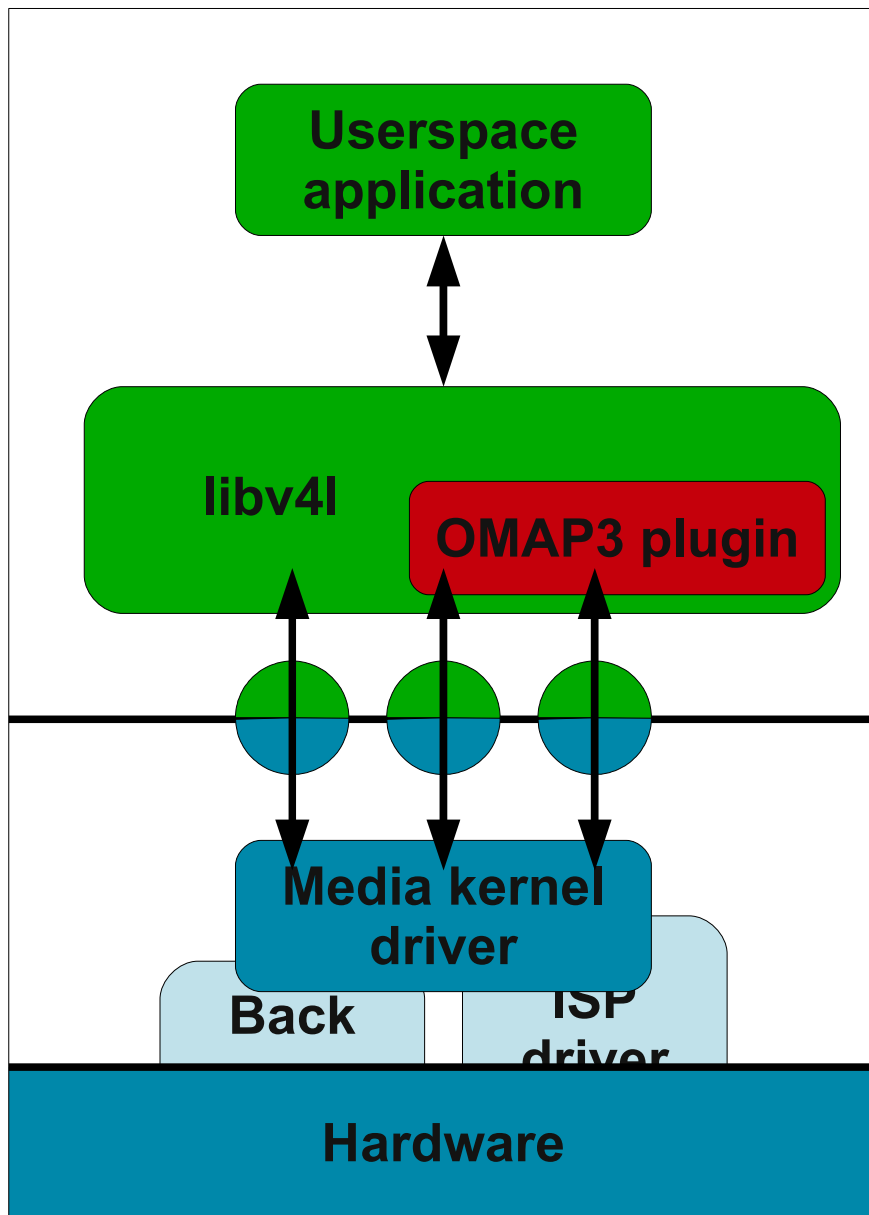
Host-side software algorithm

## Set parameters

VIDIOC\_S\_CTRL



# Image quality



- Image enhancement algorithms
- Hardware-specific acceleration
- Transparent for applications

# libv4l

- <http://gitorious.org/omap3camera>
- <http://git.ideasonboard.org/?p=media-ctl.git>



## Source code